DA180A series basic AC servo





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/ About us

Shenzhen INVT Electric Co., Ltd. (INVT for short, stock code: 002334) was founded in 2002, focusing on the fields of industrial automation and energy power. It was listed on Shenzhen Stock Exchange (SZSE) and issued A shares in 2010. Adhering to the core values of "Achieve customers, performance orientation, open and win-win cooperation, struggle and innovation" and with the mission of making every effort to offer most valuable products and services to strengthen customer competitiveness, INVT provides differentiated and specialized industry solutions, customized technical services, global localization operations, and digital management models to global customers.

Core competitiveness

Company scale: In 2023, the total operating revenue was approximately RMB 4.59 billion, a year-on-year increase of 12.03%. The net profit was approximately 371 million Yuan, a year-on-year increase of 35.06%. The total assets reached 5.186 billion Yuan, a year-on-year increase of 6.13%. INVT has 4 large bases of production and research, 15 holding subsidiaries, and over 5000 employees.

R&D capability: INVT is a national key high-tech enterprise in China's Torch Program and a drafting unit for the national standard of low-voltage VFDs.

It has established a strict quality management system and passed CNAS certification. The R&D testing laboratory has been awarded the Acceptance of Client Testing (ACT) accreditation by TUV-SUD in Germany, and the main products are CE-compliant. INVT has also been recognized as the National Enterprise Technology Center, and Guangdong Engineering Technology Research Center, and has undertaken a number of national, provincial and municipal

science and technology projects. By the end of 2023, INVT has 1538 patents and 283 computer software copyrights.

Marketing and service network: INVT has set up dozens of branches and hundreds of joint warranty centers around the world, and has established strong cooperative relationships with many domestic and international channel partners. This comprehensive sales and service network enables INVT to respond quickly to global market demands and provide immediate technical support and quality after-sales service.

Business segments

Industrial automation: Offering VFDs, servo systems, motors, controllers, human-machine interfaces, sensors, elevator drive systems, industrial internet, and other products and integrated solutions, which are widely used in compressors, cranes, solar pumps, printing and packaging machinery, 3C electronics, lithium-ion battery equipment, semiconductor equipment, offshore equipment, iron and steel, petroleum, chemical industry, and other fields.

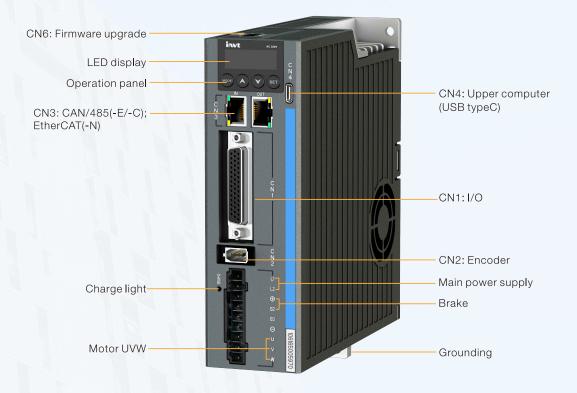
Network power: Offering micro module data centers, power supply and distribution products, intelligent temperature control products, intelligent monitoring products, and integrated solutions, which are widely used in cloud data centers, finance, communication, medical, energy, and other fields.

New energy vehicle: Offering comprehensive products such as main motor controllers, auxiliary motor controllers, vehicle controllers, and onboard power supplies, covering the full range of solutions for commercial vehicles and passenger cars.

PV energy storage: Offering grid-tie inverters, energy storage inverters, off-grid inverters, monitoring accessories, which have been applied in many scenarios at home and abroad.



/ Introduction



Simple look, utility power

INVT DA180A series basic AC servo drive

DA180A series basic AC servo drive, the new generation of INVT simplified single-axis servo product, is utility oriented, making expansion easy. It provides efficient and competitive solutions for the simplification, networking, and high-performance requirements of general-purpose equipment.

/ Features



High speed response

With a response frequency up to 2.5kHz, DA180A can significantly improve processing speed, shorten tuning time, and maximize mechanical performance



Light and compact

Compared to DA200, DA180A is up to 45% smaller in size, with flexible driving and handy control, saving installation space and achieving device miniaturization



Accurate positioning

17bits magnetic and 23bits optic absolute optical



Enriched communication interfaces

Support bus communication protocols such as Modbus, CANopen, and EtherCAT. Long-distance, multi-axis high-speed synchronous control is achieved through networking



Environmental adaptability

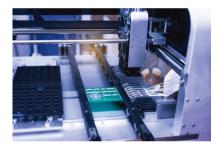
Models with an output current of 2.8A use an independent heat sink for natural cooling



Long guarantee

24 months

Applications







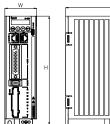
Drive model naming

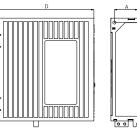
DA180A-E-2R8-S-2 Item **Description** Product series DA180A: Servo drive series E: Pulse type C: CANopen bus type (dynamic brake) Product category N: EtherCAT bus type (dynamic brake) 2R8: 2.8A Rated output current 6R0: 6.0A Voltage class S: 220V Encoder category 2: Communication encoder

/ Drive ratings and frame sizes

Drive model	Function description		Input		Frame	
Drive model	Fulletion description	Voltage (v)	Rated current (A)	Power(kw)	Rated current (A)	size
DA180A-E-2R8-S-2	Pulse+12bits analog	1PH 220	3.6	0.4	2.8	Α
DA180A-C-2R8-S-2	Pulse+CANopen+dynamic brake	1PH 220	3.6	0.4	2.8	Α
DA180A-N-2R8-S-2	EtherCAT+dynamic brake	1PH 220	3.6	0.4	2.8	Α
DA180A-E-6R0-S-2	Pulse+12bits analog	1PH 220	9.1	1.0	6	Α
DA180A-C-6R0-S-2	Pulse+CANopen+dynamic brake	1PH 220	9.1	1.0	6	А
DA180A-N-6R0-S-2	EtherCAT+dynamic brake	1PH 220	9.1	1.0	6	Α

/ Drive dimensions





Unit: mm

	Frame	Drive model	Outlin	e dime	ensions	Insta dimer	lation sions	Installation				
			Н	W	D	Α	В	hole				
		DA180A-E-2R8-S-2				37	161	M4(Φ5)				
		DA180A-C-2R8-S-2	172		157							
	Α	DA180A-N-2R8-S-2		50								
	A	DA180A-E-6R0-S-2		172	172	172	172	172	50	137	31	101
		DA180A-C-6R0-S-2										
		DA180A-N-6R0-S-2										

/ EMI filter

Drive model	EMI filter model
DA180A-E-2R8-S-2	
DA180A-C-2R8-S-2	
DA180A-N-2R8-S-2	FLT-PS2010H-B
DA180A-E-6R0-S-2	FLI-PS2010N-B
DA180A-C-6R0-S-2	
DA180A-N-6R0-S-2	

Note: EMI filter models in the table are EMI filter models of our company. Used for power input side.

/ Brake resistor

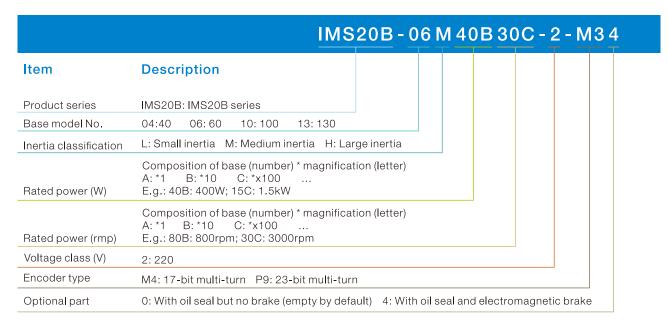
Drive model	Built-in braking resistor specifications	Min. allowed resistance of external braking resistor
DA180A-E-2R8-S-2	-	60Ω
DA180A-C-2R8-S-2	-	60Ω
DA180A-N-2R8-S-2	-	60Ω
DA180A-E-6R0-S-2	45 Ω 60W	45Ω
DA180A-C-6R0-S-2	45Ω 60W	45Ω
DA180A-N-6R0-S-2	45Ω 60W	45Ω

/ Drive introduction

			DA180A series s	ervo drive (400W/1kW)				
	Specific	ations		Description				
Power	220V Syster	m input voltage	1PH, AC 220V(±15%),	47–63Hz				
supply	Control	Input	10 inputs (The function (7 inputs for EtherCAT	n is configurable through parameter settings.) models.)				
	signal	Output	2/4 differential outputs	s (The function is configurable through parameter settings.)				
	Analog	Input	Two 12bit analog inpu	ts (None for EtherCAT models.)				
	Pulse signal	Input	Two groups (mode: open collector input or differential input)					
_	ŭ	Output	One group differential output (A+, A-; B+, B-; Z+, Z-); One group open collector output (A, B, Z					
Port	Encoder	Input	2/4-PPR absolute encoder interface					
		USB RS485	1:1 communication upper PC software 1:n communication (optional)					
	Communi- cation	CANopen	1:n communication (or					
	oation	EtherCAT	1:n communication (or	,				
	Control r		 Position control; Position/Speed mode. Position/Torque mode. 	Speed control; 3. Torque control; de switching; 5. Speed/Torque mode switching; de switching; 7. CANopen mode; 8. EtherCAT mode				
		Control input	3. Electronic gear ratio	aring;2. Command pulse input disabled; o switching;4. Vibration control switching, etc				
		Control output	0 '					
			Max. pulse input frequency	Optical coupling: differential input 4Mpps, open collector input 200kpps				
		Pulse input	Pulse input mode	1. Pulse +direction;2. CW +CCW; 3. Quadrature				
	Position	r disc iripat	Electronic gear (e-gear)					
	control		Filter	1. Command smoothing filter;2. FIR filter				
		Analog input	Torque limit command input	Can independently perform clockwise/counterclockwise torque limit				
		Vibration control	Able to suppress 1-200Hz front-end vibration and overall machine vibration					
		Pulse output	 Can perform arbitrary frequency division settings under the encoder resolution; B phase reverse function 					
		Control input	3. Internal command s	peed 1; 2. Internal command speed 2; peed 3; 4. Zero speed clamp, etc.				
		Control output	Speed reaching, etc Speed command	The speed command input can be set according to the analog				
		Analog input	input Torque limit input	voltage DC ±10V Can independently perform clockwise/counterclockwise torque limit				
uc		Internal speed						
Function	Speed	commands	8 step speed can be s	witched according to the external control input				
Fur	control	ACC/DEC adjustment of speed command	ACC/DEC time setting and S curve setting					
		Zero-speed clamp	In the speed mode, it o	can set the operation mode as the speed mode and position mode				
		Speed command filter	A delay filter of analog	input speed command				
		Speed command zero drift control	Zero drift control again	nst outside interference				
		Control input	Zero speed clamp inpu	ut, etc				
		Control output	Speed reaching, etc	A de la la companya d'accident de la companya de la				
	Томошь	Speed limit	Torque command input	Analog torque command input, gain and polarity can be set based on analog voltage				
	Torque control	Torque	Speed limit input Set the speed limit by	Analog speed limit				
		command filter		input torque command				
		Torque command zero drift control		nst outside interference				
		Plan bits	128 bits internal position	n planning, the positioning can be controlled through communication				
	Internal	Route setting	1. Position; 2. Speed;	3. ACC time; 4. DEC time;				
	position plan	ŭ		us state output; 7. Operational mode				
	ριαπ	Homing	1. LS signal; 2. Z phase signal; 3. LS signal+Z phase signal; 4. Torque limit signal					

	DA180A series servo drive (400W/1kW)						
	Specifications	Description					
Protection	Protection function	Such as protection against phase-loss, overvoltage, undervoltage, overcurrent, overheating, storage fault, initialization fault, I/O distribution abnormalities and large position deviation, braking resistor overload, and drive overload.					
rote	Dynamic braking	For emergency stop function, including stop and fault stop scenarios.					
Protection and fault record 1. U		1. Up to 10 faults can be recorded; 2. The key parameters can be recorded when fault occurs.					
	Working temperature	0-55°C (Derate 80% when the ambient temperature is 45-55°C.)					
ent	Storage temperature	-20°C-70°C (No freezing)					
E	Operation/storage humidity	≤90%RH (no condensation)					
≣nvironment	IP rating	IP20					
Altitude		Lower than 1000m					
Vibration ≤5.88m/s2, 10-60Hz (Working at the resonance point is not allowed)							

/ Motor model naming

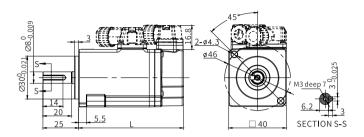


/ Servo motor technical parameters

Motor model	Rated power (kW)	Rated current (A)	Max. transient current (A)	Rated torque (Nm)		Rated speed (rpm)	speed	Rotation inertia Standard/With brake (kg·cm²)	Voltage (V)	Weight Standard/ With brake (kg)
IMS20B-04L10B30C-2-□	0.1	0.98	3.9	0.32	1.12	3000	6000	0.031/0.034	220	0.36/0.55
IMS20B-06M20B30C-2-□	0.2	1.3	4.4	0.64	2.23	3000	6000	0.34/0.35	220	0.8/1.2
IMS20B-06M40B30C-2-□	0.4	2.6	8.6	1.27	4.445	3000	6000	0.59/0.6	220	1.2/1.6
IMS20B-08M75B30C-2-□	0.75	4.6	16.3	2.38	8.36	3000	6000	1.72/1.77	220	2.2/2.9
IMS20B-08M10C30C-2-□	1	6.3	20.9	3.18	11.3	3000	6000	2.23/2.28	220	2.6/3.3
IMS20B-10M10C30C-2-□	1	6.6	19.8	3.18	9.55	3000	6000	1.84/2.59	220	3.3/4.1
IMS20B-13M85B30C-2-□	0.85	6.2	14.9	5.4	13.5	1500	4500	13.1/14.3	220	5.7/7.3
IMS20B-13M10C20C-2-□	1	5.4	16.9	4.8	14.3	2000	4500	6.3/7.95	220	4.4/6.0
Insulation class		Class F(155°C)								
IP rating		IP65/IP67 (IMS20B)								
Application environment				T	emperatur	e: - 10°0	C~+40°	C (non-frozen)		

/ Servo motor dimensions

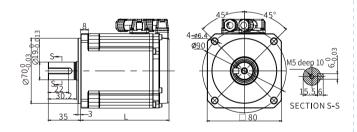
Dimensions for base-40 motors



Unit: mm

	L			
Motor model	Without brake	Electromagnetic brake		
IMS20B-04L10B30C-2-□-□	73.4	100.1		

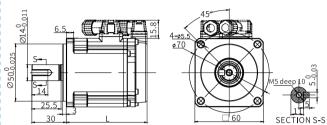
Dimensions for base-80 motors



Unit: mm

	L			
Motor model	Without brake	Electromagnetic brake		
IMS20B-08M75B30C-2-□-□	94.6	107.9		
IMS20B-08M10C30C-2-□-□	107.9	142.1		

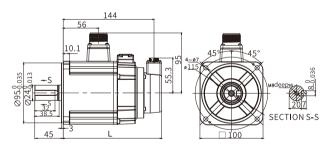
Dimensions for base-60 motors



Unit: mm

	L			
Motor model	Without brake	Electromagnetic brake		
IMS20B-06M20B30C-2-□-□	70.5	99.7		
IMS20B-06M40B30C-2-□-□	88	117.2		

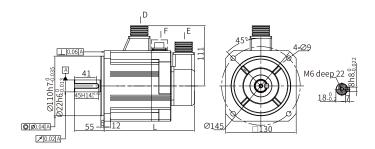
Dimensions for base-100 motors



Unit: mm

	L			
Motor model	Without brake	Electromagnetic brake		
IMS20B-10M10C30C-2-□	127.4	156		

Dimensions for base-130 motors





	L			
Motor model	Without brake	Electromagnetic brake		
IMS20B-13M85B30C-2-□	138	167		
IMS20B-13M10C20C-2-□	130	159		



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/ Servo motor power cable

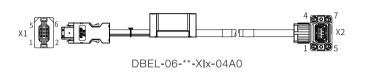
PS: ## as 00 (means without brake); ## as 01 (means with brake)

	Wiring mapping				
	Definition	X1	Х2	Core wire color	
Power cable for base-40/60/80 100–1000W motors					
	U	Tubular terminal	X2.2	Red	
→ B A A .	V	Tubular terminal	X2.1	White	
X1 4 X2	W	Tubular terminal	X2.3	Black	
271-19	PE	Ground terminal	X2.4	Yellow/green	
DAML-050-**-XFx-01	BK+	Tubular terminal	X2.A	Blue	
	BK-	Tubular terminal	X2.B	Brown	
Power cable for base-100 850–1000W motors					
	U	Tubular terminal	X2.A	Red	
	V	Tubular terminal	X2.B	White	
X1	W	Tubular terminal	X2.C	Black	
	PE	Ground terminal	X2.D	Yellow/green	
DAML-100-**-HFx-01	BK+	Tubular terminal	X2.1	Brown	
	BK-	Tubular terminal	X2.2	Blue	
Power cable for base 130 100~1000W motor					
30-F	U	Tubular terminal	X2.2	Yellow	
XI 🚉	V	Tubular terminal	X2.3	Green	
	W	Tubular terminal	X2.4	Red	
DAML-100-**-BFx-00	PE	Ground terminal	X2.1	Yellow/green	

Servo motor encoder cable

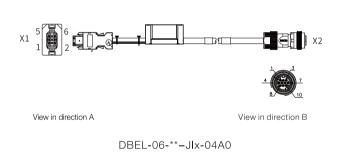
PS: ** means length, you can choose (03,05,10,15,20,25) meters; x means cable type, you can choose (0: standard F: flexible D: standard with battery H: flexible with battery)

Cable for 17-bit and 23-bit absolute encoder used by base-40/60/80 motors



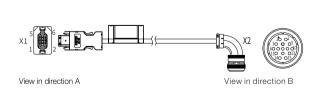
Wiring mapping									
Signal	X1	X2	Core wire						
SD+	X1.5	X2.1							
SD-	X1.6	X2.2							
5V	X1.1	X2.5	Twisted pair						
GND	X1.2	X2.6	rwisted pair						
VB+	/	X2.3							
VB-	/	X2.4							
PE	Metal shell	X2.7	Braid						

Cable for 17-bit and 23-bit absolute encoder used by base-100 motors



Wiring mapping									
Signal	X1	X2	Core wire						
SD+	X1.5	X2.1							
SD-	X1.6	X2.2							
5V	X1.1	X2.4	Twisted pair						
GND	X1.2	X2.9	rwisted pail						
VB+	/	X2.6							
VB-	/	X2.5							
PE	Metal shell	X2.1	Braid						

Cable for 17-bit and 23-bit absolute encoder used by base-130 motors



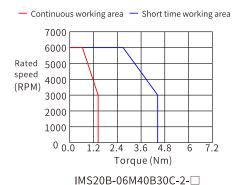
DBEL-06-**-Blx-04A0

Wiring mapping									
Signal	X1	X2	Core wire						
SD+	X1.5	X2.2							
SD-	X1.6	X2.3							
5V	X1.1	X2.4	Twisted pair						
GND	X1.2	X2.5	Twisted pair						
VB+	/	X2.6							
VB-	/	X2.7							
PE	Metal shell	X2.1	Braid						

/ TN curve of machine

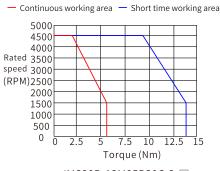


IMS20B-04L10B30C-2-□

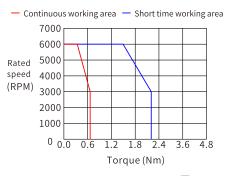


Continuous working area — Short time working area 7000 6000 Rated 5000 speed 4000 2000 1000 0 2.5 5 7.5 10 12.5 15 Torque (Nm)

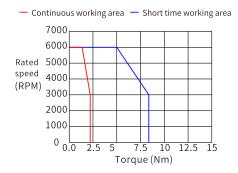
IMS20B-08M10C30C-2-□



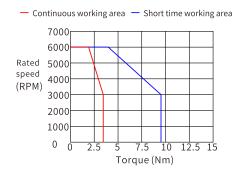
IMS20B-13M85B30C-2-□



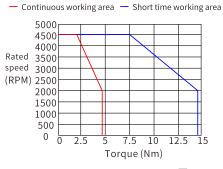
IMS20B-06M20B30C-2-□



IMS20B-08M75B30C-2-□



IMS20B-10M10C30C-2-□



IMS20B-13M10C20C-2-□

/ Servo configuration

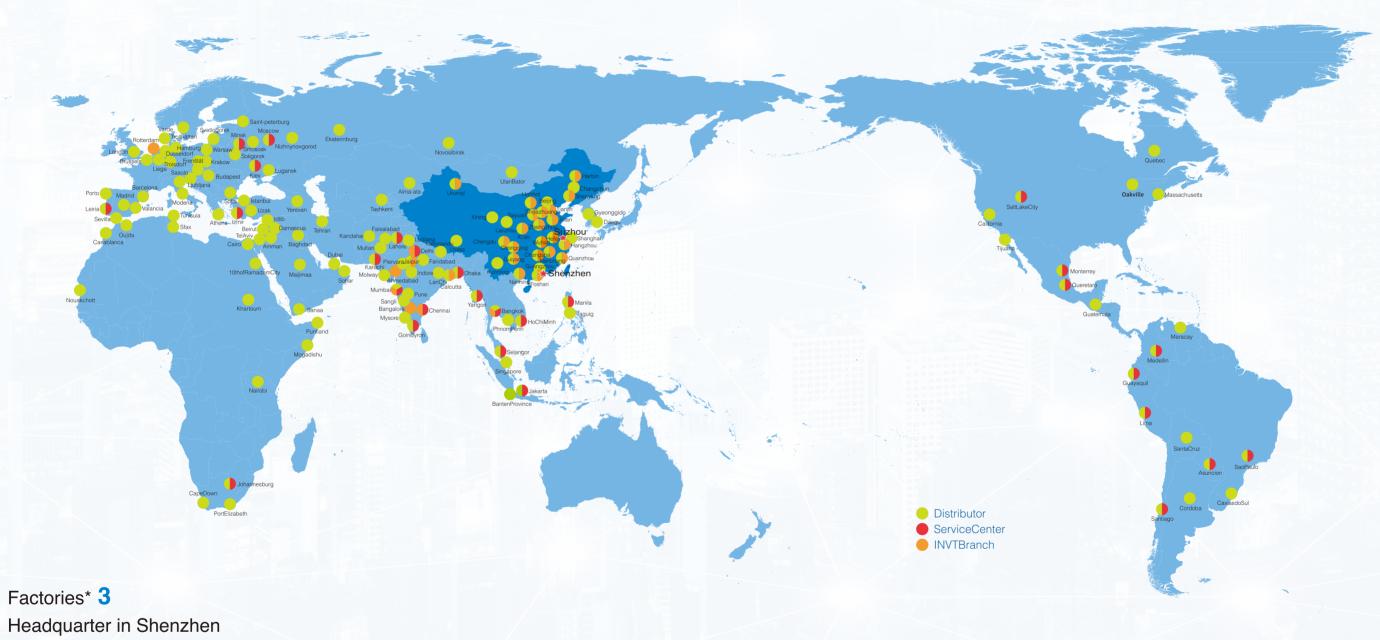
Flang (mm)				Rated current (A)	Rated voltage (V)	Inertia (kg/cm²)	Motor ERP	Motor model	Encoder	Brake	Remark	Adapted Drive	Power cable type (length: 3,5,7,10,15,20,25meter)	Encoder cable type (length: 3,5,7,10,15,20,25meter)
40	0.1	3000	0.3	0.98	220	0.031	91015-00068	IMS20B-04L10B30C-2-M4-J	17bits multi-turn magnetic	/	Plug type B			
	0.1	3000	0.3	0.98	220	0.034	91015-00069	IMS20B-04L10B30C-2-M44-J	17bits multi-turn magnetic	EM Brake	Plug type B		Standard: DAML-050-xx-XF0-00 Flexible with brake: DAML-050-xx-XFF-00 Standard with brake: DAML-050-xx-XF0-01 Flexible with brake: DAML-050-xx-XFF-01	Without battery Standard: DBEL-04-xx-XI0-04A0 Flexible with brake: DBEL-04-xx-XIF-04A0 With battery Standard: DBEL-06-xx-XID-04A0 Flexible with brake: DBEL-06-xx-XIH-04A0
40	0.1	3000	0.3	0.98	220	0.031	91015-00070	IMS20B-04L10B30C-2-P9-J	23bits multi-turn optical	/	Plug type B			
	0.1	3000	0.3	0.98	220	0.034	91015-00071	IMS20B-04L10B30C-2-P94-J	23bits multi-turn optical	EM Brake	Plug type B			
	0.2	3000	0.64	1.3	220	0.34	91015-00072	IMS20B-06M20B30C-2-M4-J	17bits multi-turn magnetic	/	Plug type B			
	0.2	3000	0.64	1.3	220	0.35	91015-00073	IMS20B-06M20B30C-2-M44-J	17bits multi-turn magnetic	EM Brake	Plug type B	DA180A-*-2R8-S-2		
	0.2	3000	0.64	1.3	220	0.34	91015-00074	IMS20B-06M20B30C-2-P9-J	23bits multi-turn optical	/	Plug type B	DA100A 2110 0 2		
60	0.2	3000	0.64	1.3	220	0.35	91015-00075	IMS20B-06M20B30C-2-P94-J	23bits multi-turn optical	EM Brake	Plug type B			
00	0.4	3000	1.27	2.6	220	0.59	91015-00076	IMS20B-06M40B30C-2-M4-J	17bits multi-turn magnetic	/	Plug type B			
	0.4	3000	1.27	2.6	220	0.6	91015-00077	IMS20B-06M40B30C-2-M44-J	17bits multi-turn magnetic	EM Brake	Plug type B			
	0.4	3000	1.27	2.6	220	0.59	91015-00078	IMS20B-06M40B30C-2-P9-J	23bits multi-turn optical	/	Plug type B			
	0.4	3000	1.27	2.6	220	0.6	91015-00079	IMS20B-06M40B30C-2-P94-J	23bits multi-turn optical	EM Brake	Plug type B		xx means lenth, eg: 03-3m	
	0.75	3000	2.39	4.6	220	1.72	91015-00080	IMS20B-08M75B30C-2-M4-J	17bits multi-turn magnetic	/	Plug type B	DA180A-*-6R0-S-2	xx meal	xx means lenth, eg: 03-3m
	0.75	3000	2.39	4.6	220	1.77	91015-00081	IMS20B-08M75B30C-2-M44-J	17bits multi-turn magnetic	EM Brake	Plug type B			
	0.75	3000	2.39	4.6	220	1.72	91015-00082	IMS20B-08M75B30C-2-P9-J	23bits multi-turn optical	/	Plug type B			
80	0.75	3000	2.39	4.6	220	1.77	91015-00083	IMS20B-08M75B30C-2-P94-J	23bits multi-turn optical	EM Brake	Plug type B			
00	1	3000	3.18	6.3	220	2.23	91015-00084	IMS20B-08M10C30C-2-M4-J	17bits multi-turn magnetic	/	Plug type B			
	1	3000	3.18	6.3	220	2.28	91015-00085	IMS20B-08M10C30C-2-M44-J	17bits multi-turn magnetic	EM Brake	Plug type B			
	1	3000	3.18	6.3	220	2.23	91015-00086	IMS20B-08M10C30C-2-P9-J	23bits multi-turn optical	/	Plug type B			
	1	3000	3.18	6.3	220	2.28	91015-00087	IMS20B-08M10C30C-2-P94-J	23bits multi-turn optical	EM Brake	Plug type B			
	1	3000	3.18	6.6	220	1.84	91015-00088	IMS20B-10M10C30C-2-M4-J	17bits multi-turn magnetic	/	Aviation plug		Standard: DAML-100-xx-GF0-00	Without battery: Standard: DBEL-04-xx-JI0-04A0
100	1	3000	3.18	6.6	220	2.59	91015-00089	IMS20B-10M10C30C-2-M44-J	17bits multi-turn magnetic	EM Brake	Aviation plug		Flexible with brake: DAML-100-xx-GFF-00 Standard with brake: DAML-100-xx-HF0-01	Flexible with brake: DBEL-04-xx-JIF-04A0 With battery
100	1	3000	3.18	6.6	220	1.84	91015-00090	IMS20B-10M10C30C-2-P9-J	23bits multi-turn optical	/	Aviation plug		Flexible with brake: DAML-100-xx-HFF-01	Standard: DBEL-06-xx-JID-04A0 Flexible with brake: DBEL-06-xx-JIH-04A0 xx means lenth, eg: 03-3m
	1	3000	3.18	6.6	220	2.59	91015-00091	IMS20B-10M10C30C-2-P94-J	23bits multi-turn optical	EM Brake	Aviation plug		xx means lenth, eg: 03-3m	
	0.85	1500	5.4	6.2	220	13.1	11101-01256	IMS20B-13H85B15C-2-M4-A	17bits multi-turn magnetic	/	Aviation plug	DA180A-*-6R0-S-2 Standard: DAML-100-xx-BF0-00 Flexible with brake: DAML-100-xx-BFF-00 xx means lenth, eg: 03-3m		
130	0.85	1500	5.4	6.2	220	14.3	11101-01255	IMS20B-13H85B15C-2-M44-A	17bits multi-turn magnetic	EM Brake	Aviation plug			Without battery Standard: DBEL-04-xx-BI0-04A0 Flexible with brake: DBEL-04-xx-BIF-04A0
	0.85	1500	5.4	6.2	220	13.1	11101-01257	IMS20B-13H85B15C-2-P9-A	23bits multi-turn optical	/	Aviation plug			
	0.85	1500	5.4	6.2	220	14.3	11101-01259	IMS20B-13H85B15C-2-P94-A	23bits multi-turn optical	EM Brake	Aviation plug			
	1	2000	4.8	5.4	220	6.3	11101-01258	IMS20B-13M10C20C-2-M4-A	17bits multi-turn magnetic	/	Aviation plug		With battery Standard: DBEL-06-xx-BID-04A0 Flexible with brake: DBEL-06-xx-BIH-04A0 xx means lenth, eg: 03-3m	
	1	2000	4.8	5.4	220	7.95	11101-01253	IMS20B-13M10C20C-2-M44-A	17bits multi-turn magnetic	EM Brake	Aviation plug			
	1	2000	4.8	5.4	220	6.3	11101-01243	IMS20B-13M10C20C-2-P9-A	23bits multi-turn optical	/	Aviation plug			
	1	2000	4.8	5.4	220	7.95	11101-01251	IMS20B-13M10C20C-2-P94-A	23bits multi-turn optical	EM Brake	Aviation plug			

PS: Encoder type, you can choose M3 (17-bits single turn magnetic), M4 (17-bits multi turn magnetic), P9 (23-bits multi turn optic absolute)

* In drive model means fieldbus type, you can choose E (plus), C (CANopen), N (EtherCAT)

10

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