

EP50S Series

Diameter ø50mm Shaft type Absolute Rotary Encoder

■ Features

- Compact size of external diameter ø50mm
- Various output code: BCD, Binary, Gray code
- Various and high resolution(720, 1024 divisions)
- Protection structure IP64(Dust-proof, Oil-proof)

■ Applications

- Precision machine tool, Fabric machinery, Robot, Parking system

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

EP50S	8	-	1024	-	1	-	R	-	P	-	24
Series	Shaft diameter		Pulse/1 Revolution		Output code		Revolution direction		Control output		Power supply
Diameter ø50mm shaft type	ø8mm		Refer to resolution		1 : BCD Code 2 : Binary Code 3 : Gray Code		F : Output value increase at CW direction R : Output value increase at CCW direction		P : PNP open collector output N : NPN open collector output		5 : 5VDC ±5% 24 : 12-24VDC ±5%

■ Specifications

Item		Diameter ø50mm shaft type of absolute rotary encoder								
Resolution		6, 8, 10, 12, 16, 20, 24, 32, 40, 45, 48, 64, 90, 128, 180, 256, 360, 512, 720, 1024								
Electrical specification	Output code		BCD Code	Binary Code	Gray Code		BCD Code	Binary Code	Gray Code	
	Output phase / Output angle※1	1024-division	TS: 0.3515°±15' (13bit)	TS: 0.3515°±15' (10bit)	TS: 0.703°±15' (10bit)	20-division	TP1:12°±60'(1bit) TP2:2°±60'(1bit) TS: 18°±60'(5bit) EP: 18°±60'(1bit)	TP1: 12°±60'(1bit) TP2: 2°±60'(1bit) TS: 18°±60'(5bit) EP: 18°±60'(1bit)	TP1: 12°±60'(1bit) TP2: 2°±60'(1bit) TS: 36°±60'(5bit) EP: 18°±60'(1bit)	
		720-division	TS: 0.5°±25' (11bit)	TS: 0.5°±25' (10bit)	TS: 1°±25' (10bit)					
		512-division	TS: 0.703°±15' (11bit)	TS: 0.703°±15' (9bit)	TS: 1.406°±15' (9bit)					
		360-division	TS: 1°±25'(10bit)	TS: 1°±25'(9bit)	TS: 2°±25'(9bit)	16-division	TP1: 15°±60'(1bit) TP2:2°±60'(1bit) TS: 22.5°±60' (5bit) EP: 22.5°±60' (1bit)	TP1:15°±60'(1bit) TP2:2°±60'(1bit) TS: 22.5°±60' (4bit) EP: 22.5°±60' (1bit)	TP1:15°±60'(1bit) TP2: 2°±60'(1bit) TS:45°±60'(4bit) EP: 22.5°±60' (1bit)	
		256-division	TS: 1.406°±15' (10bit)	TS: 1.406°±15' (8bit)	TS: 2.8125°±15' (8bit)					
		180-division	TS: 2°±25'(9bit)	TS: 2°±25'(8bit)	TS: 4°±25'(8bit)					
		128-division	TS: 2.8125°±15' (9bit)	TS: 2.8125°±15' (7bit)	TS: 5.625°±15' (7bit)					
		90-division	TS: 4°±25'(8bit)	TS: 4°±25'(7bit)	TS: 8°±25'(7bit)	12-division	TP1:15°±60'(1bit) TP2:3°±60'(1bit) TS:30°±60'(5bit) EP:30°±60'(1bit)	TP1: 15°±60'(1bit) TP2: 3°±60'(1bit) TS: 30°±60'(4bit) EP: 30°±60'(1bit)	TP1: 15°±60'(1bit) TP2: 3°±60'(1bit) TS: 60°±60'(4bit) EP: 30°±60'(1bit)	
		64-division	TS: 5.625°±15'(7bit)	TS: 5.625°±15'(6bit)	TS: 11.25°±15'(6bit)					
		48-division	TS: 7.5°±25'(7bit)	TS: 7.5°±25'(6bit)	TS: 15°±25'(6bit)					
		45-division	TS: 8°±25'(7bit)	TS: 8°±25'(6bit)	TS: 16°±25'(6bit)	10-division	TP1:30°±60'(1bit) TP2: 12°±60'(1bit) TS: 36°±60'(4bit) EP: 36°±60'(1bit)	TP1: 30°±60'(1bit) TP2: 12°±60'(1bit) TS: 36°±60'(4bit) EP: 36°±60'(1bit)	TP1: 30°±60'(1bit) TP2: 12°±60'(1bit) TS: 72°±60'(4bit) EP: 36°±60'(1bit)	
		40-division	TP1: 5°±60'(1bit) TP2: 2°±60'(1bit) TS: 9°±60'(6bit) EP: 9°±60'(1bit)	TP1: 5°±60'(1bit) TP2: 2°±60'(1bit) TS: 9°±60'(6bit) EP: 9°±60'(1bit)	TP1: 5°±60'(1bit) TP2: 2°±60'(1bit) TS: 18°±60'(6bit) EP: 9°±60'(1bit)					
		32-division	TP1:7°±60'(1bit) TP2: 2°±60'(1bit) TS: 11.25°±60'(6bit) EP: 11.25°±60'(1bit)	TP1:7°±60'(1bit) TP2: 2°±60'(1bit) TS: 11.25°±60'(5bit) EP: 11.25°±60'(1bit)	TP1: 7°±60'(1bit) TP2: 2°±60'(1bit) TS: 22.5°±60'(5bit) EP: 11.25°±60'(1bit)	10-division	TP1:39°±60'(1bit) TP2: 15°±60'(1bit) TS: 45°±60'(3bit) EP: 45°±60'(1bit)	TP1: 39°±60'(1bit) TP2: 15°±60'(1bit) TS: 45°±60'(3bit) EP: 45°±60'(1bit)	TP1: 39°±60'(1bit) TP2: 15°±60'(1bit) TS: 90°±60'(3bit) EP: 45°±60'(1bit)	
		24-division	TP1: 8°±60'(1bit) TP2: 3°±60'(1bit) TS: 15°±60'(6bit) EP: 15°±60'(1bit)	TP1: 8°±60'(1bit) TP2: 3°±60'(1bit) TS: 15°±60'(5bit) EP: 15°±60'(1bit)	TP1: 8°±60'(1bit) TP2: 3°±60'(1bit) TS: 30°±60'(5bit) EP: 15°±60'(1bit)	6-division	TP1: 53°±60'(1bit) TP2: 15°±60'(1bit) TS: 60°±60'(3bit) EP: 60°±60'(1bit)	TP1:53°±60'(1bit) TP2: 15°±60'(1bit) TS: 60°±60'(3bit) EP: 60°±60'(1bit)	TP1: 53°±60'(1bit) TP2: 15°±60'(1bit) TS: 120°±60'(3bit) EP: 60°±60'(1bit)	
Control output	PNP open collector output	Output voltage : Min. (Power supply-1.5)VDC, Load current : Max. 32mA								
	NPN open collector output	Load current : Max. 32mA, Residual voltage : Max. 1VDC								
Response time(Rise/Fall)		Ton=800nsec, Toff=Max. 800nsec(Cable length : 2m, I sink = 32mA)								
Max. Response frequency		35kHz								
Power supply		• 5VDC ±5%(Ripple P-P : Max. 5%) • 12-24VDC ±5%(Ripple P-P : Max. 5%)								
Current consumption		Max. 100mA(disconnection of the load)								
Insulation resistance		Min. 100MΩ(at 500VDC megger between all terminals and case)								
Dielectric strength		750VAC 50/60Hz for 1 minute(Between all terminals and case)								
Connection		Cable type(Cable gland)								

※1: TS=Signal Pulse, Tp=Timing Pulse, EP=Even Parity

ø50mm Shaft Absolute type

■ Specifications

Item	Diameter ø50mm shaft type of absolute rotary encoder	
Mechanical specification	Starting torque	Max. 40gf·cm(0.004N·m)
	Moment of inertia	Max. 40g·cm ² (4×10 ⁻⁶ kg·m ²)
	Shaft loading	Radial : 10kgf, Thrust : 2.5kgf
	Max. allowable revolution ^{※2}	3000rpm
Vibration	1.5mm amplitude or 300m/s ² at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours	
Shock	Approx. Max. 50G	
Environment	Ambient temperature	-10 to 70°C, storage : -25 to 85°C
	Ambient humidity	35 to 85%RH, storage : 35 to 90%RH
Protection	IP64(IEC standard)	
Cable	ø7, 15-wire, Length : 2m, Shield cable(AWG 28, Core diameter: 0.08mm, Number of cores: 40, Insulator out diameter: ø0.8)	
Accessory	Fixing bracket, Coupling	
Approval	CE	
Unit weight	Approx. 380g	

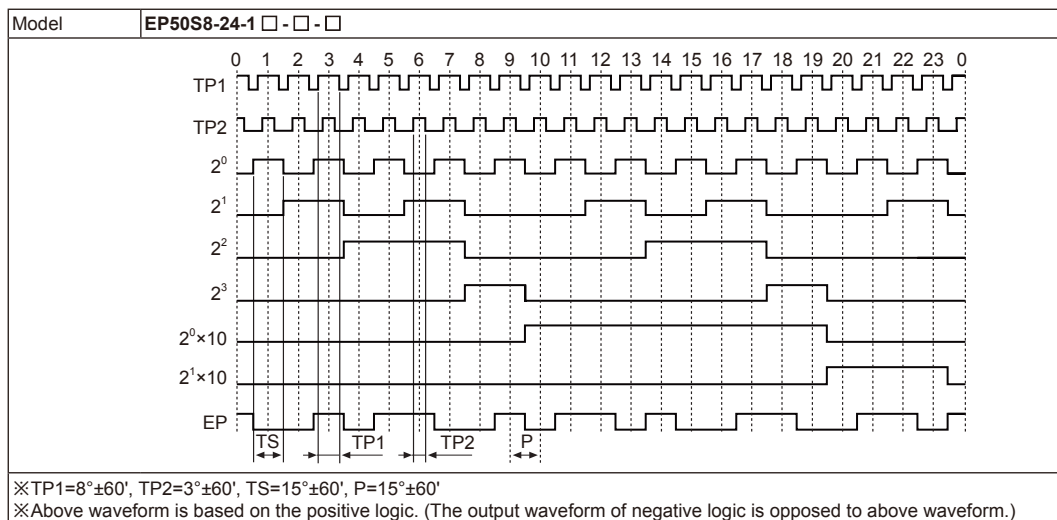
※2: Make sure that. Max response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

$$[\text{Max. response revolution(rpm)}] = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$$

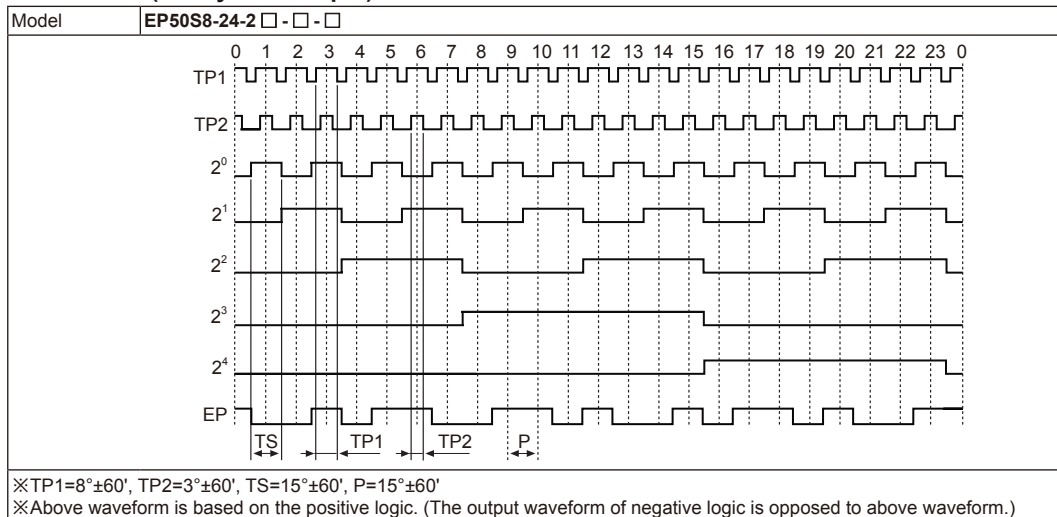
※Environment resistance is rated at no freezing or condensation.

■ Output waveform

● 24 division (BCD code output)



● 24 division (Binary code output)



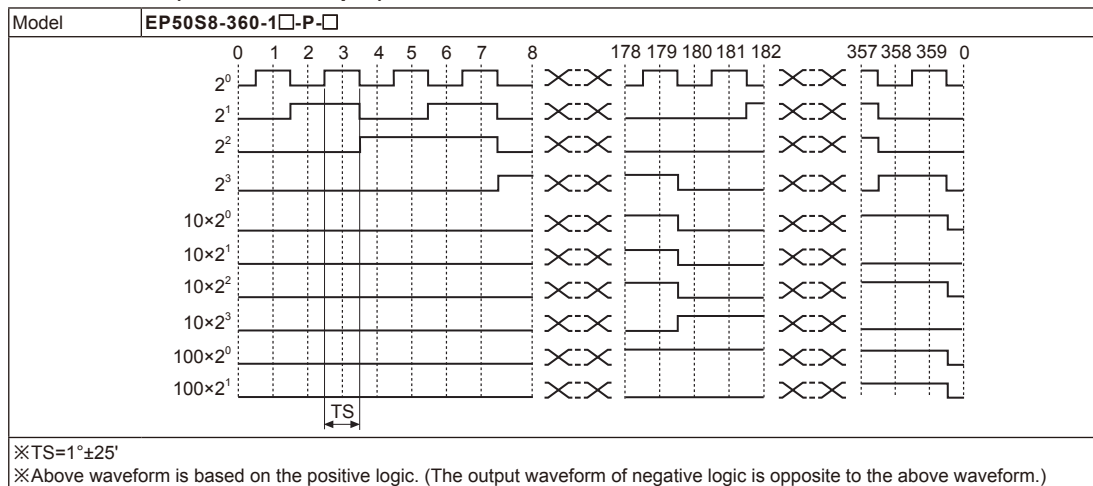
(A)	Photo electric sensor
(B)	Fiber optic sensor
(C)	Door/Area sensor
(D)	Proximity sensor
(E)	Pressure sensor
(F)	Rotary encoder
(G)	Connector/Socket
(H)	Temp. controller
(I)	SSR/Power controller
(J)	Counter
(K)	Timer
(L)	Panel meter
(M)	Tacho/Speed/ Pulse meter
(N)	Display unit
(O)	Sensor controller
(P)	Switching mode power supply
(Q)	Stepper motor& Driver&Controller
(R)	Graphic/ Logic panel
(S)	Field network device
(T)	Software
(U)	Other



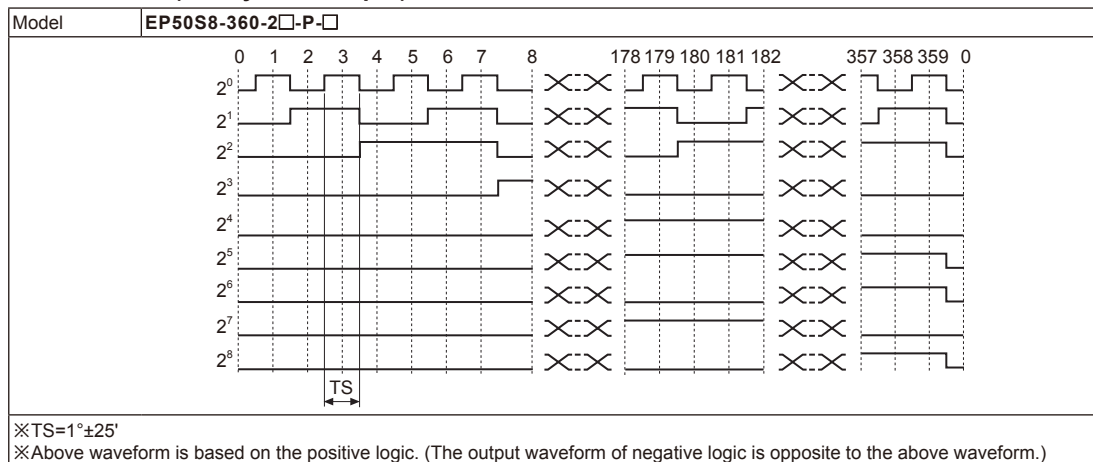
EP50S Series

■ Output waveform

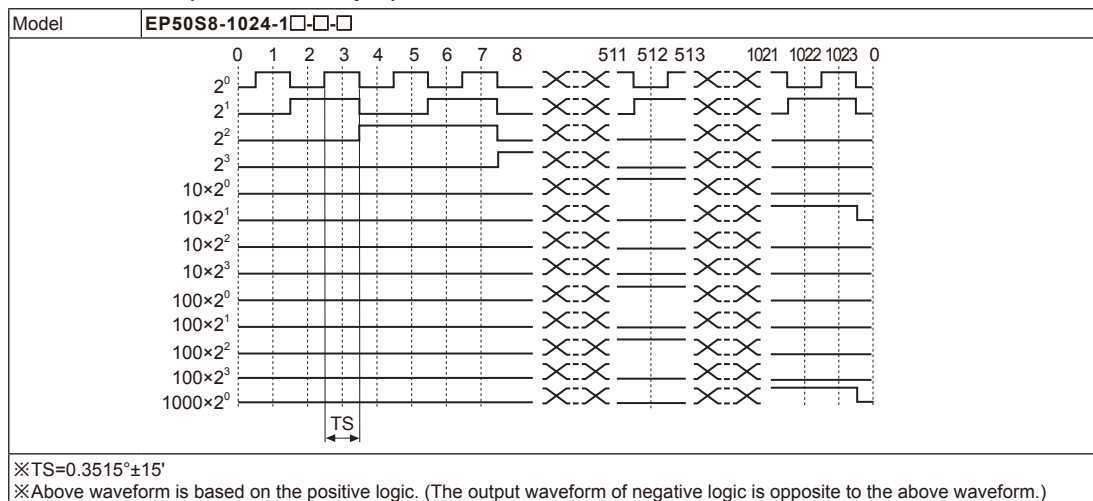
● 360 division (BCD code output)



● 360 division (Binary code output)



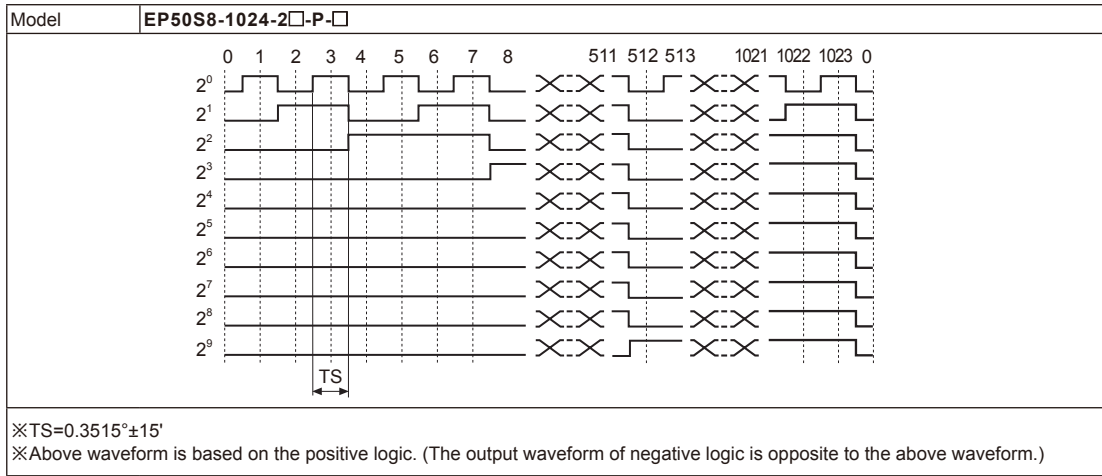
● 1024 division (BCD code output)



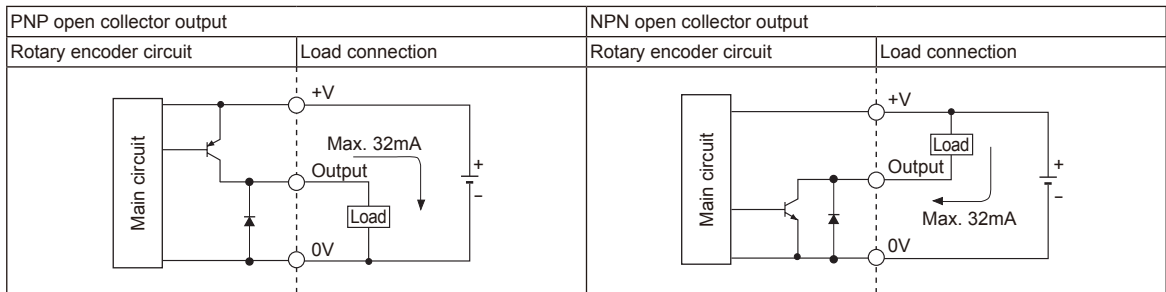
ø50mm Shaft Absolute type

■ Output waveform

● 1024 division (Binary code output)



■ Control output diagram



※Output circuits of all phases are the same.

■ Connections

● BCD Code

Resolution		6-division	8-division	10-division	12-division	16-division	20-division	24-division	32-division	40-division	45-division	48-division	64-division	90-division	128-division	80-division	256-division	360-division	512-division	720-division	1024-division	
Color																						
Power	White	+V																				
	Boack	0V																				
Output wire	Brown	2 ⁰																				
	Red	2 ¹																				
	Orange	2 ²																				
	Yellow	N·C		2 ³																		
	Blue	N·C			2 ⁰ ×10																	
	Purple	N·C							2 ²¹ ×10													
	Gray	N·C										2 ² ×10										
	White/Brown	TP1										N·C					2 ³ ×10					
	White/Red	TP2										N·C					2 ⁰ ×10					
	White/Orange	EP										N·C					2 ¹ ×100					
	White/Yellow	N·C																		2 ² ×100		
	White/Blue	N·C																			2 ³ ×100	
	White/Purple	N·C																			2 ⁰ ×1000	
	Shield wire	F.G.																				

※Unused wires must be insulated.

※Encoder case and shield wire must be grounded(F.G.).

※N-C: Not Connected.

※Output cable must not be short-circuited, because Driver IC is used in output circuit.

(A)
Photo
electric
sensor

(B)
Fiber
optic
sensor

(C)
Door/Area
sensor

(D)
Proximity
sensor

(E)
Pressure
sensor

(F)
Rotary
encoder

(G)
Connector/
Socket

(H)
Temp.
controller

(I)
SSR/
Power
controller

(J)
Counter

(K)
Timer

(L)
Panel
meter

(M)
Tacho/
Speed/
Pulse
meter

(N)
Display
unit

(O)
Sensor
controller

(P)
Switching
mode power
supply

(Q)
Stepper
motor&
Driver&Controller

(R)
Graphic/
Logic
panel

(S)
Field
network
device

(T)
Software

(U)
Other

■ Connections

- **Binary Code/Gray Code**

Resolution		6-division	8-division	10-division	12-division	16-division	20-division	24-division	32-division	40-division	45-division	48-division	64-division	90-division	128-division	80-division	256-division	360-division	512-division	720-division	1024-division
Color																					
Power	White	+V																			
	Boack	0V																			
Output wire	Brown	2 ⁰																			
	Red	2 ¹																			
	Orange	2 ²																			
	Yellow	N·C		2 ³																	
	Blue	N·C					2 ⁴														
	Purple	N·C									2 ⁵										
	Gray	N·C										2 ⁶									
	White/Brown	TP1										N·C					2 ⁷				
	White/Red	TP2										N·C					2 ⁸				
	White/Orange	EP										N·C					2 ⁹				
	Shield wire	F.G.																			

※Unused wires must be insulated.

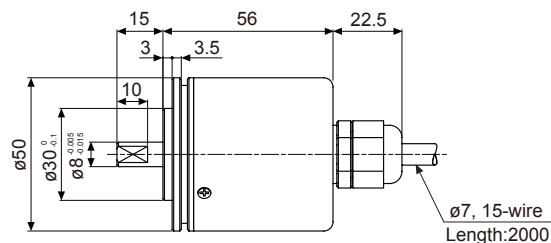
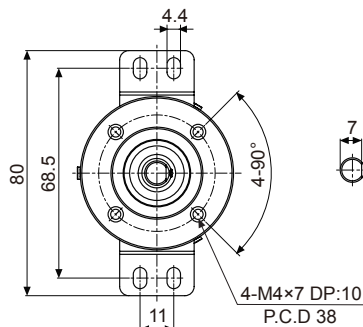
※Encoder case and shield wire must be grounded(F.G.).

※N-C: Not Connected.

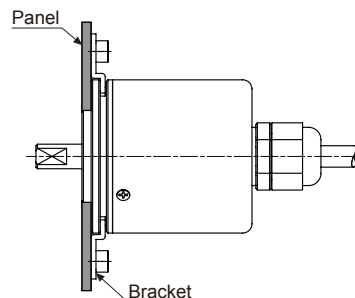
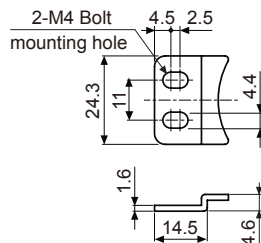
※Output cable must not be short-circuited, because Driver IC is used in output circuit.

■ Dimensions

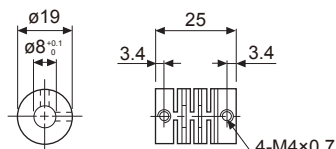
(unit: mm)



- **Bracket**



- Coupling(EP50S)



- Parallel misalignment : Max. 0.25mm
- Angular misalignment : Max. 5°
- End-play : Max. 0.2mm

※For parallel misalignment, angular misalignment, end-play terms, refer to the F-78 page.

※For flexible coupling(ERB Series) information, refer to the F-71 page.